

Maple sample file for J. ISCIE by K. Fujimoto 2011.03

step 1

```
CodeGeneration[ Matlab ] ( arcsin( x ) );
cg = asin(x);
```

step 2

```
diff( sin( x1^2 + x1·x2 ), x1 );
cos( x1^2 + x1 x2 ) ( 2 x1 + x2 )
```

(1)

step 3

```
with( VectorCalculus ) :
F := [ tan( x2 ), u / cos( x2 ) ] :
Jacobian( F, [ x1, x2, u ] );
```

$$\begin{bmatrix} 0 & 1 + \tan(x2)^2 & 0 \\ 0 & \frac{u \sin(x2)}{\cos(x2)^2} & \frac{1}{\cos(x2)} \end{bmatrix}$$

(2)

step 4

```
int( cos( x1^2 + x1·x2 ) · ( 2·x1 + x2 ), x1 );
sin( x1^2 + x1 x2 )
```

(3)

step 5

```
g := [ x2^2, 2·x1·x2 ] :
Jacobian( g, [ x1, x2 ] );
```

$$\begin{bmatrix} 0 & 2 x2 \\ 2 x2 & 2 x1 \end{bmatrix}$$

(4)

```
pdsolve( [ diff( f( x1, x2 ), x1 ) = g[1],
diff( f( x1, x2 ), x2 ) = g[2] ] );
{ f( x1, x2 ) = x2^2 x1 + _C1 }
```

(5)

step 6

```
A := evalf( subs( { x1 = 0, x2 = 0, u = 0 }, Jacobian( F, [ x1, x2 ] ) ) );
```

$$\begin{bmatrix} 0. & 1. \\ 0. & 0. \end{bmatrix}$$

(6)

```
B := evalf( subs( { x1 = 0, x2 = 0, u = 0 }, diff( F, u ) ) );
[ 0., 1. ]
```

(7)

step 7

```
MyL := proc( phi, f, x, k )
local i, result;
with( VectorCalculus ) :
```

```

result := phi :
for i from 1 to k do
  result := evalm ( Jacobian ([ result ], x) &* f ) [1] :
end do:
result,
end proc:
MyL ( x1, F, [ x1, x2 ], 2);

```

$$\frac{(1 + \tan(x2)^2) u}{\cos(x2)} \quad (8)$$

```

# step 8
dsolve ( -diff ( V ( x ), x ) ·sinh ( x ) + x2 = 0 );
V ( x ) = x2 ln ( 1 - ex ) + 2 x polylog ( 2, ex ) - 2 polylog ( 3, ex ) - x2 ln ( 1 + ex )
- 2 x polylog ( 2, -ex ) + 2 polylog ( 3, -ex ) + _C1

```

$$(9)$$

```

# step 9
V4 := c1·x + c2·x2 + c3·x3 + c4·x4 :
eq4 := mtaylor ( -diff ( V4, x ) ·sinh ( x ) + x2, x, 5 ) :
match ( 0 = eq4, x, 'sol4' ) :
sol4,

```

$$\left\{ c1 = 0, c2 = \frac{1}{2}, c3 = 0, c4 = -\frac{1}{24} \right\} \quad (10)$$

```

# step 10
xx := [ x1, x2 ] :
f := [ tan ( x2 ), 0 ] :
g := [ 0, 1 / cos ( x2 ) ] :
h := x1 :
MyL ( h, g, xx, 1);

```

$$0 \quad (11)$$

```

MyL ( MyL ( h, f, xx, 1 ), g, xx, 1 );

```

$$\frac{1 + \tan(x2)^2}{\cos(x2)} \quad (12)$$

```

# step 11
alpha := - MyL ( h, f, xx, 2 ) / MyL ( MyL ( h, f, xx, 1 ), g, xx, 1 );

```

$$0 \quad (13)$$

```

beta := 1 / MyL ( MyL ( h, f, xx, 1 ), g, xx, 1 );

```

$$\frac{1}{MyL \left(\tan(x2), \left[0, \frac{1}{\cos(x2)} \right], [x1, x2], 1 \right)} \quad (14)$$

```

Phi := [ h, MyL ( h, f, xx, 1 ) ];

```

$$[x1, \tan(x2)] \quad (15)$$

step 12

$sol := pdsolve(evalm(Jacobian([\phi(x1, x2)], xx) \&* g) [1] = 0);$

$$\phi(x1, x2) = _FI(x1)$$

(16)

$fg := evalm(Jacobian(g, xx) \&* f - Jacobian(f, xx) \&* g) :$

$evalm(Jacobian([subs(sol, \phi(x1, x2))], xx) \&* fg) [1];$

$$- \frac{\left(\frac{d}{dx1} _FI(x1) \right) (1 + \tan(x2)^2)}{\cos(x2)}$$

(17)

step 13

$P := \frac{[[3, -1], [-1, 1]]}{2} :$

$V := simplify(evalm(\Phi \&* P \&* \Phi));$

$$\frac{3}{2} x1^2 - x1 \tan(x2) + \frac{1}{2} \tan(x2)^2$$

(18)

$LgV := simplify(MyL(V, g, xx, 1)) :$

$LfV := simplify(MyL(V, f, xx, 1)) :$

$ux := - \frac{(LfV + \sqrt{ LfV^2 + LgV^4 })}{LgV};$

$$\frac{1}{x1 \cos(x2) - \sin(x2)} \left(\left(-(-3 x1 + \tan(x2)) \tan(x2) \right. \right.$$

(19)

$$\left. + \sqrt{(-3 x1 + \tan(x2))^2 \tan(x2)^2 + \frac{(x1 \cos(x2) - \sin(x2))^4}{\cos(x2)^{16}}} \right) \cos(x2)^4$$