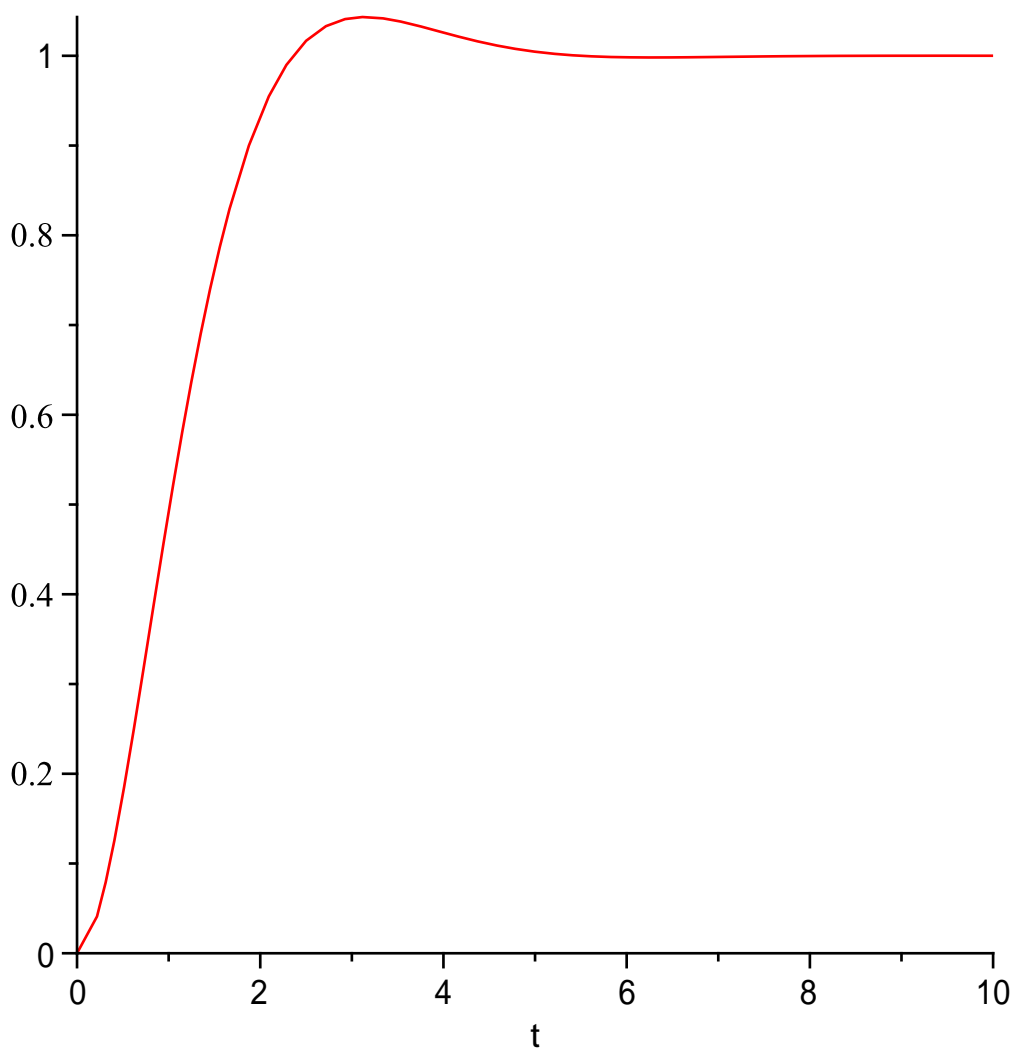


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[> # Maple sample file (math mode) for J. ISCIE by M. Kanno 2011.03
[> # システム/制御/情報 2011年5月号 (Vol. 55 No. 5)
[> # 数式処理を用いたパラメータを有する線形制御系の解析 管野 政明
[> # Section 2 - 基本操作と伝達関数
[> restart :
[> ## 基本操作
[> f := x10 - 1;
                                     f := x10 - 1
(1)
[> g := factor(f);
                                     g := (x - 1) (x + 1) (x4 + x3 + x2 + x + 1) (x4 - x3 + x2 - x + 1)
(2)
[> h := (x + 1)2 - (x2 - 1); simplify(h);
                                     h := (x + 1)2 - x2 + 1
                                     2 x + 2
(3)
[> g; expand(g);
                                     (x - 1) (x + 1) (x4 + x3 + x2 + x + 1) (x4 - x3 + x2 - x + 1)
                                     x10 - 1
(4)
[>  $\frac{x^2 - 1}{x - 1}$ ; normal(%);
                                      $\frac{x^2 - 1}{x - 1}$ 
                                     x + 1
(5)
[> ## 伝達関数
[> P :=  $\frac{2}{s + 2}$ ; K :=  $\frac{1}{s}$ ;
                                     P :=  $\frac{2}{s + 2}$ 
                                     K :=  $\frac{1}{s}$ 
(6)
[> Tcl :=  $\frac{P \cdot K}{1 + P \cdot K}$ ; Tcl := simplify(Tcl);
                                     Tcl :=  $\frac{2}{(s + 2) s \left( 1 + \frac{2}{(s + 2) s} \right)}$ 
                                     Tcl :=  $\frac{2}{s^2 + 2 s + 2}$ 
(7)
[> with(inttrans) :
[> Tcl_t := invlaplace(Tcl *  $\frac{1}{s}$ , s, t);
                                     Tcl_t := 1 - e-t (cos(t) + sin(t))
(8)
[> plot(Tcl_t, t = 0..10);

```



$$\begin{aligned} &> \lim_{t \rightarrow \infty} Tcl_t, \\ &1 \end{aligned} \tag{9}$$

$$\begin{aligned} &> \frac{d}{dt} Tcl_t, Tcl2_t := \text{simplify}(\%); \\ &\quad e^{-t} (\cos(t) + \sin(t)) - e^{-t} (-\sin(t) + \cos(t)) \\ &\quad Tcl2_t := 2 e^{-t} \sin(t) \end{aligned} \tag{10}$$

$$\begin{aligned} &> \int_0^{\infty} Tcl2_t^2 dt, \\ &\quad \frac{1}{2} \end{aligned} \tag{11}$$

$$\begin{aligned} &> g_t := \text{invlaplace}\left(\frac{1}{s+a}, s, t\right); \\ &\quad g_t := e^{-at} \end{aligned} \tag{12}$$

$$\begin{aligned} &> \lim_{t \rightarrow \infty} g_t, \\ &\quad \lim_{t \rightarrow \infty} e^{-at} \end{aligned} \tag{13}$$

$$\begin{aligned} &> \lim_{t \rightarrow \infty} g_t \text{ assuming } a > 0; \\ &\quad 0 \end{aligned} \tag{14}$$

$$\begin{aligned} &> \text{invlaplace}\left(\frac{1}{s^3 + 2 \cdot s^2 + 3 \cdot s + 4}, s, t\right); \\ &\quad \frac{1}{20} \sum_{\alpha = \text{RootOf}(_Z^3 + 2 _Z^2 + 3 _Z + 4)} e^{-\alpha t} (-_ \alpha + _ \alpha^2) \end{aligned} \quad (15)$$

$$\begin{aligned} &> \text{evalf}(\%); \\ &0.2187602960 e^{-1.650629191 t} + (-0.1093801480 \\ &\quad + 0.1043649860 I) e^{(-0.1746854043 - 1.546868887 I) t} + (-0.1093801480 \\ &\quad - 0.1043649860 I) e^{(-0.1746854043 + 1.546868887 I) t} \end{aligned} \quad (16)$$

$$\begin{aligned} &> \# \text{Section 3 - パラメータを有する線形系の安定性} \\ &> \text{with}(\text{PolynomialTools}) : \text{with}(\text{LinearAlgebra}) : \\ &> \text{read "HurwitzMatrix.maple"}; \\ &> [\text{seq}(a \parallel i, i = 0 .. 5)]; p := \text{sort}(\text{FromCoefficientList}(\%, s)); \\ &\quad [a0, a1, a2, a3, a4, a5] \\ &\quad p := a5 s^5 + a4 s^4 + a3 s^3 + a2 s^2 + a1 s + a0 \end{aligned} \quad (17)$$

$$\begin{aligned} &> Hn := \text{HurwitzMatrix}(p, s); \\ &\quad Hn := \begin{bmatrix} a4 & a2 & a0 & 0 & 0 \\ a5 & a3 & a1 & 0 & 0 \\ 0 & a4 & a2 & a0 & 0 \\ 0 & a5 & a3 & a1 & 0 \\ 0 & 0 & a4 & a2 & a0 \end{bmatrix} \end{aligned} \quad (18)$$

$$\begin{aligned} &> \# \text{if 文を用いたプロシージャ} \\ &> \text{read "HurwitzMatrix2.maple"}; \\ &> Hn2 := \text{HurwitzMatrix2}(p, s); \\ &\quad Hn2 := \begin{bmatrix} a4 & a2 & a0 & 0 & 0 \\ a5 & a3 & a1 & 0 & 0 \\ 0 & a4 & a2 & a0 & 0 \\ 0 & a5 & a3 & a1 & 0 \\ 0 & 0 & a4 & a2 & a0 \end{bmatrix} \end{aligned} \quad (19)$$

$$\begin{aligned} &> Hn - Hn2; \\ &\quad \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \end{aligned} \quad (20)$$

$$\begin{aligned} &> \# \text{同じ結果が得られた} \\ &> p := \text{convert}(s^3 + (1.03 + q) \cdot s^2 + (1.02 + 3 \cdot q) \cdot s + (1.01 + 7 \cdot q), \text{rational}, \text{exact}); \\ &\quad p := s^3 + \left(\frac{103}{100} + q\right) s^2 + \left(\frac{51}{50} + 3 q\right) s + \frac{101}{100} + 7 q \\ &> Hn := \text{HurwitzMatrix}(p, s); \end{aligned} \quad (21)$$

$$H_n := \begin{bmatrix} \frac{103}{100} + q & \frac{101}{100} + 7q & 0 \\ 1 & \frac{51}{50} + 3q & 0 \\ 0 & \frac{103}{100} + q & \frac{101}{100} + 7q \end{bmatrix} \quad (22)$$

$$\begin{aligned} &> f := \text{sort}(\text{Determinant}(H_n)); \\ &f := 21q^3 - \frac{86}{5}q^2 - \frac{26347}{10000}q + \frac{20503}{500000} \end{aligned} \quad (23)$$

$$\begin{aligned} &> \text{roots}_f := \text{sort}(\text{realroot}(f, 10^{-8})); \text{evalf}(\text{roots}_f); \\ \text{roots}_f := &\left[\left[-\frac{19365701}{134217728}, -\frac{4841425}{33554432} \right], \left[\frac{1913879}{134217728}, \frac{239235}{16777216} \right], \left[\frac{127382531}{134217728}, \right. \right. \\ &\left. \left. \frac{31845633}{33554432} \right] \right] \\ &[[-0.1442857161, -0.1442857087], [0.01425950974, 0.01425951719], [0.9490738139, \\ &0.9490738213]] \end{aligned} \quad (24)$$

$$\begin{aligned} &> \text{subs}(q = \text{roots}_f[1][1] - 1, p); \text{Hurwitz}(\%, s); \\ &s^3 - \frac{383479229}{3355443200}s^2 - \frac{8096205111}{3355443200}s - \frac{23488102443}{3355443200} \end{aligned} \quad (25)$$

$$\begin{aligned} &> \text{Hurwitz}\left(\text{subs}\left(q = \frac{\text{roots}_f[1][2] + \text{roots}_f[2][1]}{2}, p\right), s\right); \\ &\text{true} \end{aligned} \quad (26)$$

$$\begin{aligned} &> \text{Hurwitz}\left(\text{subs}\left(q = \frac{\text{roots}_f[2][2] + \text{roots}_f[3][1]}{2}, p\right), s\right); \\ &\text{false} \end{aligned} \quad (27)$$

$$\begin{aligned} &> \text{Hurwitz}(\text{subs}(q = \text{roots}_f[3][2] + 1, p), s); \\ &\text{true} \end{aligned} \quad (28)$$

Section 4 - パラメータを有する線形系のH2ノルム

$$\begin{aligned} &> A := \begin{bmatrix} -a & -1 \\ 1 & 0 \end{bmatrix}; B := \begin{bmatrix} 1 \\ 0 \end{bmatrix}; C := \begin{bmatrix} 2 & -1 \end{bmatrix}; \\ &A := \begin{bmatrix} -a & -1 \\ 1 & 0 \end{bmatrix} \\ &B := \begin{bmatrix} 1 \\ 0 \end{bmatrix} \\ &C := \begin{bmatrix} 2 & -1 \end{bmatrix} \end{aligned} \quad (29)$$

$$\begin{aligned} &> \text{sort}(\text{simplify}(C.(s \cdot \text{IdentityMatrix}(2) - A)^{-1}.B), s); \\ &\frac{2s - 1}{s^2 + as + 1} \end{aligned} \quad (30)$$

$$\begin{aligned} &> Lo := \text{Matrix}(2, \text{symbol}=l, \text{shape}=\text{symmetric}); \\ & \end{aligned} \quad (31)$$

$$Lo := \begin{bmatrix} l_{1,1} & l_{1,2} \\ l_{1,2} & l_{2,2} \end{bmatrix} \quad (31)$$

> ## solve の使い方

$$> \text{solve}(x^2 - 2); \quad \sqrt{2}, -\sqrt{2} \quad (32)$$

$$> \text{solve}(x^2 - a, x); \quad \sqrt{a}, -\sqrt{a} \quad (33)$$

$$> \text{solve}(x^2 - a); \quad \{a = x^2, x = x\} \quad (34)$$

$$> \text{solve}(x^2 - a, \{x\}); \quad \{x = \sqrt{a}\}, \{x = -\sqrt{a}\} \quad (35)$$

$$> \text{solve}(\{2 \cdot x + y = 3, x - y = 0\}); \quad \{x = 1, y = 1\} \quad (36)$$

> ## solve の使い方 - 終わり

$$> Lyap := \text{Transpose}(A).Lo + Lo.A + \text{Transpose}(C).C; \\ Lyap := \begin{bmatrix} -2a l_{1,1} + 2l_{1,2} + 4 & -a l_{1,2} + l_{2,2} - l_{1,1} - 2 \\ -a l_{1,2} + l_{2,2} - l_{1,1} - 2 & -2l_{1,2} + 1 \end{bmatrix} \quad (37)$$

$$> \text{convert}(Lo, \text{set}); \quad \{l_{1,1}, l_{1,2}, l_{2,2}\} \quad (38)$$

$$> sol := \text{solve}(\text{convert}(Lyap, \text{set}), \text{convert}(Lo, \text{set})); \\ sol := \left\{ l_{1,1} = \frac{5}{2a}, l_{1,2} = \frac{1}{2}, l_{2,2} = \frac{1}{2} \frac{a^2 + 5 + 4a}{a} \right\} \quad (39)$$

$$> \text{subs}(sol, Lo); \text{Transpose}(B). \%B; \\ \begin{bmatrix} \frac{5}{2a} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \frac{a^2 + 5 + 4a}{a} \end{bmatrix} \\ \frac{5}{2a} \quad (40)$$

> # end

>